

TWO REMARKS ON PQ^ϵ -PROJECTIVITY OF RIEMANNIAN METRICS

VLADIMIR S. MATVEEV AND STEFAN ROSEMANN

ABSTRACT. We show that PQ^ϵ -projectivity of two Riemannian metrics introduced in [15] implies affine equivalence of the metrics unless $\epsilon \in \{0, -1, -3, -5, -7, \dots\}$. Moreover, we show that for $\epsilon = 0$, PQ^ϵ -projectivity implies projective equivalence.

1. INTRODUCTION

1.1. **PQ^ϵ -projectivity of Riemannian metrics.** Let g, \bar{g} be two Riemannian metrics on an m -dimensional manifold M . Consider $(1, 1)$ -tensors P, Q which satisfy

$$(1) \quad \begin{aligned} g(P., .) &= -g(., P), & g(Q., .) &= -g(., Q) \\ \bar{g}(P., .) &= -\bar{g}(., P), & \bar{g}(Q., .) &= -\bar{g}(., Q) \\ PQ &= \epsilon Id, \end{aligned}$$

where Id is the identity on TM and ϵ is a real number, $\epsilon \neq 1, m + 1$. The following definition was introduced in [15].

Definition 1. The metrics g, \bar{g} are called PQ^ϵ -projective if for a certain 1-form Φ the Levi-Civita connections ∇ and $\bar{\nabla}$ of g and \bar{g} satisfy

$$(2) \quad \bar{\nabla}_X Y - \nabla_X Y = \Phi(X)Y + \Phi(Y)X - \Phi(PX)QY - \Phi(PY)QX$$

for all vector fields X, Y .

Example 1. If the two metrics g and \bar{g} are *affinely equivalent*, i.e. $\nabla = \bar{\nabla}$, then they are PQ^ϵ -projective with P, Q, ϵ arbitrary and $\Phi \equiv 0$.

Example 2. Suppose that $\Phi(P) = 0$ or $Q = 0$ and $\epsilon = 0$. It follows that equation (2) becomes

$$(3) \quad \bar{\nabla}_X Y - \nabla_X Y = \Phi(X)Y + \Phi(Y)X.$$

By Levi-Civita [4], equation (3) is equivalent to the condition that g and \bar{g} have the same geodesics considered as unparametrized curves, i.e., that g and \bar{g} are *projectively equivalent*. The theory of projectively equivalent metrics has a very long tradition in differential geometry, see for example [13, 10, 7, 5, 6] and the references therein.

Example 3. Suppose that $P = Q = J$ and $\epsilon = -1$. It follows that J is an almost complex structure, i.e., $J^2 = -Id$, and by (1) the metrics g and \bar{g} are required to be hermitian with respect to J . Equation (2) now reads

$$(4) \quad \bar{\nabla}_X Y - \nabla_X Y = \Phi(X)Y + \Phi(Y)X - \Phi(JX)JY - \Phi(JY)JX.$$

This equation defines the *h-projective equivalence* of the hermitian metrics g and \bar{g} and was introduced for the first time by Otsuki and Tashiro in [12, 14] for Kählerian metrics. The theory of *h-projectively equivalent* metrics was introduced as an analog of projective geometry in the Kählerian situation and has been studied actively over the years, see for example [11, 3, 1, 2, 8] and the references therein.

Remark 1. PQ^ϵ -projectivity of Riemannian metrics is a special case of so-called *F-planar mappings* introduced and investigated in [9], whose defining equation [9, (1)] clearly generalises equation (2) above.

Institute of Mathematics, FSU Jena, 07737 Jena Germany,
vladimir.matveev@uni-jena.de, stefan.rosemann@uni-jena.de.
partially supported by GK 1523 of DFG.

1.2. Results. The aim of our paper is to give a proof of the following two theorems:

Theorem 1. *Let Riemannian metrics g and \bar{g} be PQ^ϵ -projective. If g and \bar{g} are not affinely equivalent, the number ϵ is either zero or an odd negative integer, i.e., $\epsilon \in \{0, -1, -3, -5, -7, \dots\}$.*

Theorem 2. *Let Riemannian metrics g and \bar{g} be PQ^ϵ -projective. If $\epsilon = 0$ then g and \bar{g} are projectively equivalent.*

1.3. Motivation and open questions. As it was shown in [15], PQ^ϵ -projectivity of the metrics g, \bar{g} allows us to construct a family of commuting integrals for the geodesic flow of g (see Fact 2 and equation (9) below). The existence of these integrals is an interesting phenomenon on its own. Besides, it appeared to be a powerful tool in the study of projectively equivalent and h -projectively equivalent metrics (Examples 2,3), see [3, 7, 5, 6, 8]. Moreover, in [15] it was shown that given one pair of PQ^ϵ -projective metrics, one can construct an infinite family of PQ^ϵ -projective metrics. Under some non-degeneracy condition, this gives rise to an infinite family of integrable flows.

From the other side, the theories of projectively equivalent and h -projectively equivalent metrics appeared to be very useful mathematical theories of deep interest.

The results in our paper suggest to look for other examples in the case when $\epsilon = -1, -3, -5, \dots$. If $\epsilon = -1$ but $P^2 \neq -Id$, a lot of examples can be constructed using the "hierarchy construction" from [15]. It is interesting to ask whether every pair of PQ^{-1} -projective metrics is in the hierarchy of some h -projectively equivalent metrics.

Another attractive problem is to find interesting examples for $\epsilon = -3, -5, \dots$. Besides the relation to integrable systems provided by [15], one could find other branches of differential geometry of similar interest as projective or h -projective geometry.

1.4. PDE for PQ^ϵ -projectivity. Given a pair of Riemannian metrics g, \bar{g} and tensors P, Q satisfying (1), we introduce the $(1, 1)$ -tensor $A = A(g, \bar{g})$ defined by

$$(5) \quad A = \left(\frac{\det \bar{g}}{\det g} \right)^{\frac{1}{m+1-\epsilon}} \bar{g}^{-1} g.$$

Here we view the metrics as vector bundle isomorphisms $g : TM \rightarrow T^*M$ and $\bar{g}^{-1} : T^*M \rightarrow TM$. We see that A is non-degenerate and self-adjoint with respect to g and \bar{g} . Moreover A commutes with P and Q .

Fact 1 (Lemma 2 in [15], see also Theorems 5,6 in [9]). *Two metrics g and \bar{g} are PQ^ϵ -projective if for a certain vector field Λ , the $(1, 1)$ -tensor A defined in (5) is a solution of*

$$(6) \quad (\nabla_X A)Y = g(Y, X)\Lambda + g(Y, \Lambda)X + g(Y, QX)P\Lambda + g(Y, P\Lambda)QX \text{ for all } X, Y \in TM.$$

Conversely, if A is a g -self-adjoint positive solution of (6) which commutes with P and Q , the Riemannian metric

$$\bar{g} = (\det A)^{-\frac{1}{1-\epsilon}} g A^{-1}$$

is PQ^ϵ -projective to g .

Remark 2. Taking the trace of the $(1, 1)$ -tensors in equation (6) acting on the vector field Y , we obtain

$$(7) \quad \Lambda = \frac{1}{2(1-\epsilon)} \text{grad trace } A,$$

hence, (6) is a linear first order PDE on the $(1, 1)$ -tensor A .

Remark 3. From Fact 1 it follows that the metrics g, \bar{g} are affinely equivalent if and only if $\Lambda \equiv 0$ on the whole M .

Remark 4. The relation between the 1-form Φ in (2) and the vector field Λ in (6) is given by $\Lambda = -Ag^{-1}\Phi$ (again $g^{-1} : T^*M \rightarrow TM$ is considered as a bundle isomorphism), see [15]. Recall from Example 2 that projective equivalence is a special case of PQ^ϵ -projectivity with $\Phi(P) = 0$ or $Q = 0$ and $\epsilon = 0$. In view of Fact 1, we now have that g and \bar{g} are projectively equivalent if and only if $A = A(g, \bar{g})$ given by (5) (with $\epsilon = 0$), satisfies (6) with $P\Lambda = 0$ or $Q = 0$, i.e.,

$$(8) \quad (\nabla_X A)Y = g(Y, X)\Lambda + g(Y, \Lambda)X \text{ for all } X, Y \in TM.$$

2. PROOF OF THE RESULTS

2.1. **Topalov's integrals.** We first recall

Fact 2 (Proposition 3 in [15]). *Let g and \bar{g} be PQ^ϵ -projective metrics and let A be defined by (5). We identify TM with T^*M by g , and consider the canonical symplectic structure on $TM \cong T^*M$. Then the functions $F_t : TM \rightarrow \mathbb{R}$,*

$$(9) \quad F_t(X) = |\det(A - tId)|^{\frac{1}{1-\epsilon}} g((A - tId)^{-1}X, X), \quad X \in TM$$

are commuting quadratic integrals for the geodesic flow of g .

Remark 5. Note that the function F_t in equation (9) is not defined in the points $x \in M$ such that $t \in \text{spec } A|_x$. From the proof of Theorem 1 it will be clear that in the non-trivial case one can extend the functions F_t to these points as well.

2.2. **Proof of Theorem 1.** Suppose that g and \bar{g} are PQ^ϵ -projective Riemannian metrics and let $A = A(g, \bar{g})$ be the corresponding solution of (6) defined by (5). Since A is self-adjoint with respect to the positively-definite metric g , the eigenvalues of A in every point $x \in M$ are real numbers. We denote them by $\mu_1(x) \leq \dots \leq \mu_m(x)$; depending on the multiplicity, some of the eigenvalues might coincide. The functions μ_i are continuous on M . Denote by $M^0 \subseteq M$ the set of points where the number of different eigenvalues of A is maximal on M . Since the functions μ_i are continuous, M^0 is open in M . Moreover, it was shown in [15] that M^0 is dense in M as well. The implicit function theorem now implies that μ_i are differentiable functions on M^0 .

From Remark 3 and equation (7) we immediately obtain that g and \bar{g} are affinely equivalent, if and only if all eigenvalues of A are constant. Suppose that g and \bar{g} are not affinely equivalent, that is, there is a non-constant eigenvalue ρ of A with multiplicity $k \geq 1$. Let us choose a point $x_0 \in M^0$ such that $d\rho|_{x_0} \neq 0$, define $c := \rho(x_0)$ and consider the hypersurface $H = \{x \in U : \rho(x) = c\}$, where $U \subseteq M^0$ is a geodesically convex neighborhood of x_0 . We think that U is sufficiently small such that $\mu(x) \neq c$ for all eigenvalues μ of A different from ρ and all $x \in U$.

Lemma 1. *There is a smooth nowhere vanishing $(0, 2)$ -tensor T on U such that on $U \setminus H$, T coincides with*

$$(10) \quad \text{sgn}(\rho - c) |\det(A - cId)|^{\frac{1}{k}} g((A - cId)^{-1}., .).$$

Proof. Let us denote by $\rho = \rho_1, \rho_2, \dots, \rho_r$ the different eigenvalues of A on M^0 with multiplicities $k = k_1, k_2, \dots, k_r$ respectively. Since the eigenspace distributions of A are differentiable on M^0 , we can choose a local frame $\{U_1, \dots, U_m\}$ on U , such that g and A are given by the matrices

$$g = \text{diag}(1, \dots, 1) \quad \text{and} \quad A = \text{diag}(\underbrace{\rho, \dots, \rho}_{k \text{ times}}, \dots, \underbrace{\rho_r, \dots, \rho_r}_{k_r \text{ times}})$$

with respect to this frame. The tensor (10) can now be written as

$$(11) \quad \begin{aligned} & \text{sgn}(\rho - c) |\det(A - cId)|^{\frac{1}{k}} g(A - cId)^{-1} = \\ & = (\rho - c) \prod_{i=2}^r |\rho_i - c|^{\frac{k_i}{k}} \text{diag}\left(\underbrace{\frac{1}{\rho - c}, \dots, \frac{1}{\rho - c}}_{k \text{ times}}, \dots, \underbrace{\frac{1}{\rho_r - c}, \dots, \frac{1}{\rho_r - c}}_{k_r \text{ times}}\right) = \\ & = \prod_{i=2}^r |\rho_i - c|^{\frac{k_i}{k}} \text{diag}\left(\underbrace{1, \dots, 1}_{k \text{ times}}, \dots, \underbrace{\frac{\rho - c}{\rho_r - c}, \dots, \frac{\rho - c}{\rho_r - c}}_{k_r \text{ times}}\right). \end{aligned}$$

Since $\rho_i \neq c$ on $U \subseteq M^0$ for $i = 2, \dots, r$, we see that (11) is a smooth nowhere vanishing $(0, 2)$ -tensor on U . \square

Lemma 2. *The multiplicity of the non-constant eigenvalues of A is equal to $1 - \epsilon$.*

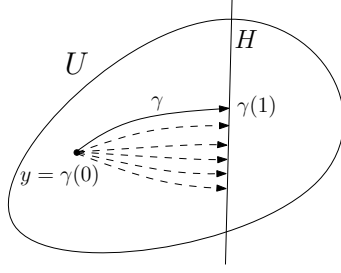


FIGURE 1. Case $\frac{1}{1-\epsilon} - \frac{1}{k} > 0$: We connect the point $y \in U \setminus H$ with the points in H by geodesics. The value of the integral F_c is zero on each of these geodesics.

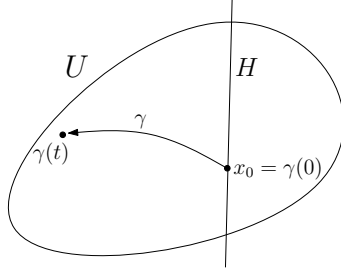


FIGURE 2. Case $\frac{1}{1-\epsilon} - \frac{1}{k} < 0$: For any geodesic γ starting in $x_0 \in H$ and leaving H , the value of the integral F_c along this geodesic is infinite.

Proof. Let us consider the integral $F_c : TM \rightarrow \mathbb{R}$ defined in equation (9). Using the tensor T from Lemma 1, we can write F_c as

$$(12) \quad F_c(X) = \underbrace{\text{sgn}(\rho - c) |\det(A - cId)|^{\frac{1}{1-\epsilon} - \frac{1}{k}}}_{=: f_c} T(X, X), \quad X \in TM.$$

Our goal is to show that $\frac{1}{1-\epsilon} - \frac{1}{k} = 0$.

First suppose that $\frac{1}{1-\epsilon} - \frac{1}{k} > 0$ and let be $y \in U \setminus H$. We choose a geodesic $\gamma : [0, 1] \rightarrow U$ such that $y = \gamma(0)$ and $\gamma(1) \in H$, see figure 1. Since $\rho(\gamma(t)) \xrightarrow{t \rightarrow 1} c$, we see from equation (12) that $f_c(\gamma(t)) \xrightarrow{t \rightarrow 1} 0$. It follows that $F_c(\dot{\gamma}(t)) \xrightarrow{t \rightarrow 1} 0$. On the other hand, since F_c is an integral for the geodesic flow of g (see Fact 2), the value $F_c(\dot{\gamma}(t))$ is independent of t and, hence, $F_c(\dot{\gamma}(0)) = 0$. We have shown that $F_c(\dot{\gamma}(0)) = 0$ for all initial velocities $\dot{\gamma}(0) \in T_y M$ of geodesics connecting y with points of H . Since H is a hypersurface, it follows that the quadric $\{X \in T_y M : F_c(X) = 0\}$ contains an open subset which implies that $F_c \equiv 0$ on $T_y M$. This is a contradiction to Lemma 1, since T is non-vanishing in y . We obtain that $\frac{1}{1-\epsilon} - \frac{1}{k} \leq 0$.

Let us now treat the case when $\frac{1}{1-\epsilon} - \frac{1}{k} < 0$. We choose a vector $X \in T_{x_0} M$ which is not tangent to H and satisfies $T(X, X) \neq 0$. Such a vector exists, since $T_{x_0} M \setminus T_{x_0} H$ is open in $T_{x_0} M$ and T is not identically zero on $T_{x_0} M$ by Lemma 1. Let us consider the geodesic γ with $\gamma(0) = x_0$ and $\dot{\gamma}(0) = X$, see figure 2. Since $X \notin T_{x_0} H$, the geodesic γ has to leave H for $t > 0$. In a point $\gamma(t) \in U \setminus H$ the value $F_c(\dot{\gamma}(t))$ will be finite. On the other hand, since $f_c(\gamma(t)) \xrightarrow{t \rightarrow 0} \infty$ and $T(\dot{\gamma}(0), \dot{\gamma}(0)) \neq 0$, we have $F_c(\dot{\gamma}(t)) \xrightarrow{t \rightarrow 0} \infty$. Again this contradicts the fact that the value of F_c must remain constant along $\dot{\gamma}$ by Fact 2. We have shown that $\frac{1}{1-\epsilon} - \frac{1}{k} = 0$ and finally, Lemma 2 is proven. \square

As a consequence of Lemma 2, if the metrics g, \bar{g} are not affinely equivalent (i.e., at least one eigenvalue of A is non-constant), ϵ is an integer less or equal to zero. If $\epsilon \neq 0$, the condition $PQ = \epsilon Id$ in (1) implies that P is non-degenerate and by the first condition in (1), $g(P, \cdot)$ is a non-degenerate 2-form on each eigenspace of A (note that A and P commute). This implies that

for $\epsilon \neq 0$ the eigenspaces of A have even dimension, in particular, $1 - \epsilon \in \{2, 4, 6, 8, \dots\}$. Theorem 1 is proven.

2.3. Proof of Theorem 2. Let g, \bar{g} be two PQ^ϵ -projective metrics and let A be the corresponding solution of equation (6) defined by (5). As it was already stated in the proof of Theorem 1, the eigenspace distributions of A are differentiable in a neighborhood of almost every point of M . First let us prove

Lemma 3. *Let X be an eigenvector of A corresponding to the eigenvalue ρ . If μ is another eigenvalue of A and $\rho \neq \mu$, then $X(\mu) = 0$. In particular, $\text{grad } \mu$ is an eigenvector of A corresponding to the eigenvalue μ .*

Remark 6. Lemma 3 is known for projectively equivalent (Example 2) and h -projectively equivalent (Example 3) metrics. For projectively equivalent metrics it is a classical result which was already known to Levi-Civita [4]. For h -projectively equivalent metrics, it follows from [1, 8].

Proof. Let Y be an eigenvector field of A corresponding to the eigenvalue μ . For arbitrary $X \in TM$, we obtain $\nabla_X(AY) = \nabla_X(\mu Y) = X(\mu)Y + \mu \nabla_X Y$ and $\nabla_X(AY) = (\nabla_X A)Y + A \nabla_X Y$. Combining these equations and replacing the expression $(\nabla_X A)Y$ by (6) we obtain

$$(13) \quad (A - \mu Id) \nabla_X Y = X(\mu)Y - g(Y, X)\Lambda - g(Y, \Lambda)X - g(Y, QX)P\Lambda - g(Y, P\Lambda)QX.$$

Now let X be an eigenvector of A corresponding to the eigenvalue ρ and suppose that $\rho \neq \mu$. Since A is g -self-adjoint, the eigenspaces of A corresponding to different eigenvalues are orthogonal to each other. Moreover, since A and Q commute, Q leaves the eigenspaces of A invariant. Using (13) we obtain

$$(A - \mu Id) \nabla_X Y + g(Y, \Lambda)X + g(Y, P\Lambda)QX = X(\mu)Y.$$

Since the left-hand side is orthogonal to the μ -eigenspace of A , we necessarily have $X(\mu) = 0$. We have shown that $g(\text{grad } \mu, X) = X(\mu) = 0$ for any eigenvalue μ and any eigenvector field X corresponding to an eigenvalue different from μ . This forces $\text{grad } \mu$ to be contained in the eigenspace of A corresponding to μ . \square

Now suppose that $\epsilon = 0$. Let us denote the non-constant eigenvalues of A by ρ_1, \dots, ρ_l . Using Lemma 2, the corresponding eigenspaces are 1-dimensional and Lemma 3 implies that they are spanned by the gradients $\text{grad } \rho_1, \dots, \text{grad } \rho_l$ respectively. Since P and A commute, P leaves the eigenspaces of A invariant, hence, $P \text{grad } \rho_i = p_i \text{grad } \rho_i$ for some real number p_i . Now P is skew with respect to g and we obtain $0 = g(\text{grad } \rho_i, P \text{grad } \rho_i) = p_i g(\text{grad } \rho_i, \text{grad } \rho_i)$ which implies that

$$P \text{grad } \rho_i = 0.$$

On the other hand, by equation (7)

$$\Lambda = \frac{1}{2} \text{grad trace } A = \frac{1}{2} (\text{grad } \rho_1 + \dots + \text{grad } \rho_l).$$

Combining the last two equations, we obtain $P\Lambda = 0$. It follows from Remark 4 that g and \bar{g} are projectively equivalent and, hence, Theorem 2 is proven.

Acknowledgements. We thank Peter Topalov for useful discussions and Deutsche Forschungsgemeinschaft (Research training group 1523 – Quantum and Gravitational Fields) and FSU Jena for partial financial support.

REFERENCES

- [1] V. Apostolov, D. Calderbank, P. Gauduchon, *Hamiltonian 2-forms in Kähler geometry. I. General theory*, J. Differential Geom. **73**, no. 3, 359–412, 2006
- [2] A. Fedorova, V. Kiosak, V. Matveev, S. Rosemann, *The only Kähler manifold with degree of mobility ≥ 3 is $(CP(n), g_{Fubini-Study})$* , arXiv:1009.5530v1 [math.DG], 2010, accepted to Proc. Lond. Math. Soc.
- [3] K. Kiyohara, P. J. Topalov, *On Liouville integrability of h -projectively equivalent Kähler metrics*, Proc. Amer. Math. Soc. **139**(2011), 231–242.
- [4] T. Levi-Civita, *Sulle trasformazioni delle equazioni dinamiche*, Ann. di math. **24**, 255–300, 1896
- [5] V. S. Matveev, *Hyperbolic manifolds are geodesically rigid*, Invent. math. **151**, no. 3, 579–609, 2003

- [6] V. S. Matveev, *Proof of the projective Lichnerowicz-Obata conjecture*, J. Diff. Geom. **75**, no. 3, 459–502, 2007
- [7] V. S. Matveev, P. J. Topalov, *Integrability in the theory of geodesically equivalent metrics*, J. Phys. A **34**, no. 11, 2415–2433, 2001
- [8] V. S. Matveev, S. Rosemann, *Proof of the Yano-Obata conjecture for holomorph-projective transformations*, arXiv:1103.5613 [math.DG], 2011
- [9] J. Mikes, *Special F-planar mappings of affinely connected spaces onto Riemannian spaces*, (English. Russian original) Mosc. Univ. Math. Bull. **49**, No. 3, 15–21, 1994; translation from Vestn. Mosk. Univ., Ser. I, No. 3, 18–24, 1994
- [10] J. Mikes, *Geodesic Mappings Of Affine-Connected And Riemannian Spaces*, Journal of Math. Sciences **78**, no. 3, 311–333, 1996
- [11] J. Mikes, *Holomorphically projective mappings and their generalizations.*, J. Math. Sci. (New York) **89**, no. 3, 1334–1353, 1998
- [12] T. Otsuki, Y. Tashiro, *On curves in Kaehlerian spaces*, Math. Journal of Okayama University **4**, 57–78, 1954
- [13] N. S. Sinjukov, *Geodesic mappings of Riemannian spaces.* (in Russian) “Nauka”, Moscow, 1979, MR0552022, Zbl 0637.53020.
- [14] Y. Tashiro, *On A Holomorphically Projective Correspondence In An Almost Complex Space*, Math. Journal of Okayama University **6**, 147–152, 1956
- [15] P. J. Topalov, *Geodesic Compatibility And Integrability Of Geodesic Flows*, Journal of Mathematical Physics **44**, no. 2, 913–929, 2003